

OPEN SOURCE TECHNOLOGIES FOR ENVI AND IDL

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Today's Speakers



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Introduction

What is Open Source?

IDL Python Bridge

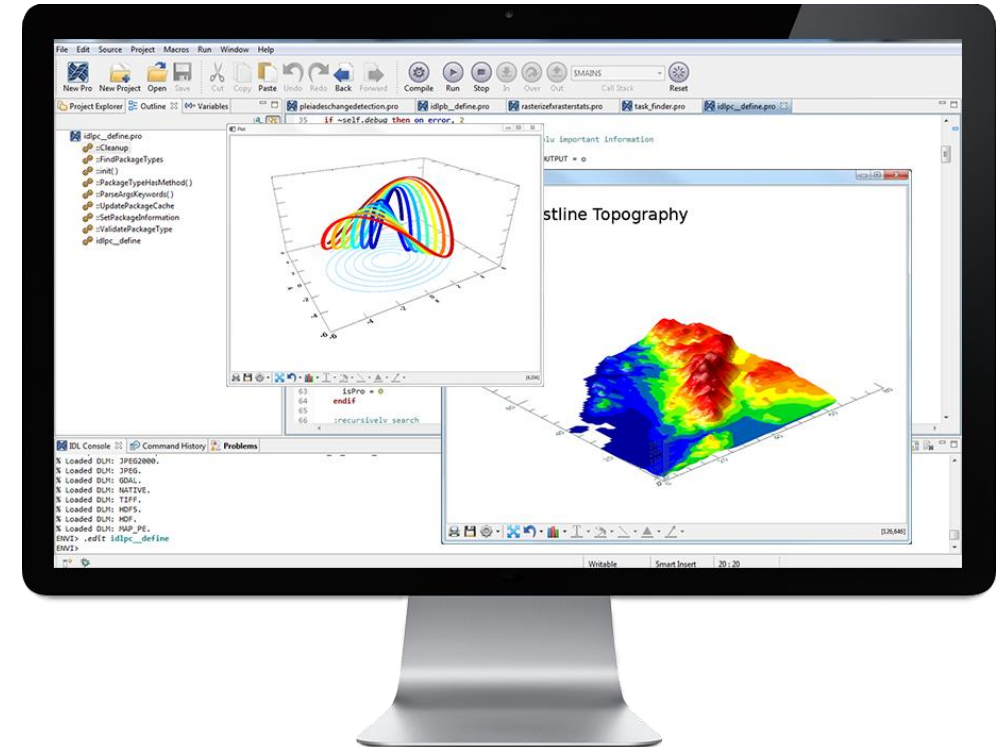
IDL Package Manager

GitHub

Upcoming Packages to GitHub

Demo!

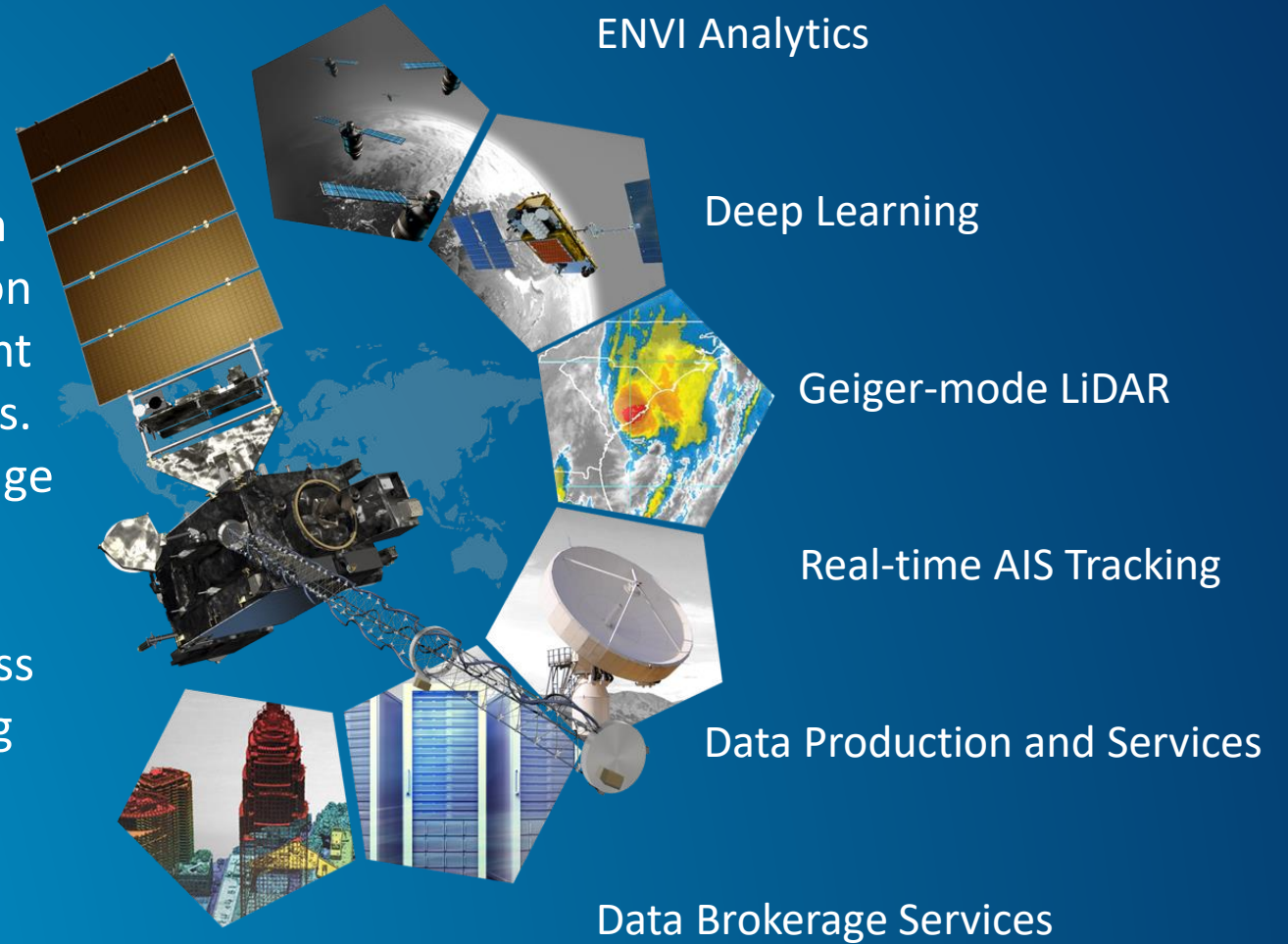
Questions

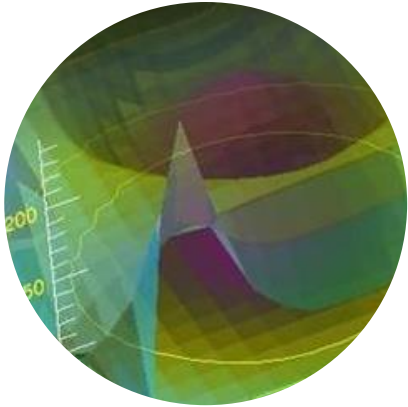


Harris Geospatial Solutions

Geospatial Solutions and Services

Harris' innovative mapping and visualization capabilities are designed to meet the mission requirements of federal and civil government as well as a broad range of commercial users. Our integrated imagery analytics, cutting edge sensor types and scalable data production and data management offerings allow the user to seamlessly gain situational awareness using advanced, easy to use, remote sensing technology.

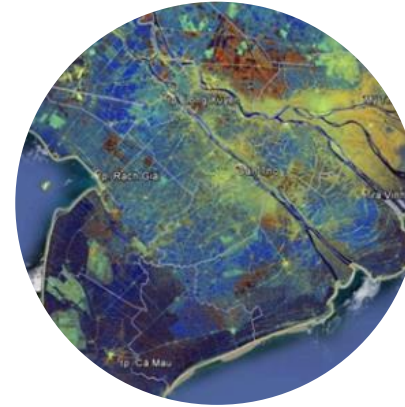




IDL



ENVI



SARscape



Geospatial Services Framework



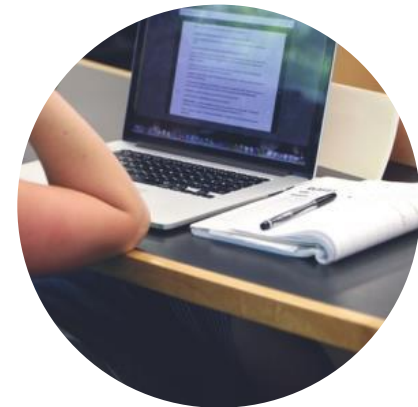
Jagwire



MapMart Marketplace



Deep Learning



Training & Consulting

What is Open Source?



The image shows a search results card for "Open-source software". At the top, there is a collage of logos including the Open Source Initiative (OSI) logo, GitHub, and various open-source hardware logos. Below the collage, the title "Open-source software" is displayed with a share icon. A paragraph of text defines open-source software as a type of computer software where source code is released under a license that grants users the rights to study, change, and distribute the software. Below the text, it says "People also search for: Free software, Cloud computing, MORE". At the bottom, there is a section titled "Open source CMS" with a "View 40+ more" link, followed by logos for WordPress, Drupal, Joomla, TYPO3, and concrete5.

open source initiative

Join in

open source hardware

More images

Open-source software

Open-source software is a type of computer software in which source code is released under a license in which the copyright holder grants users the rights to study, change, and distribute the software to anyone and for any purpose. Open-source software may be developed in a collaborative public manner. [Wikipedia](#)

People also search for: [Free software](#), [Cloud computing](#), [MORE](#)

Open source CMS

[View 40+ more](#)

WordPress Drupal Joomla! TYPO3 concrete5

**Great for community and user
driven development**

Power is in the hands of users

Want a change, you can make it!



IDL Package Manager (IPM) makes it easier for developers to share IDL code in open source ecosystems

- Create, install, update, and remove IDL packages, which are zipped files & folders
- Packages can contain IDL pro code, IDL save files, and/or IDL DLMs
- New IDL_PACKAGE_PATH preference, and the IDL path is automatically updated

IPM-ready libraries are now available

```
ipm, /install, 'https://github.com/csalvaggio/IDL_RIT_Salvaggio'  
ipm, /install, 'https://github.com/hadfieldnz/idl-motley'  
ipm, /install, 'https://github.com/hadfieldnz/idl-roms'  
ipm, /install, 'https://github.com/mankoff/kdm-idl'  
ipm, /install, 'http://packages.idldev.com/idldoc.zip'  
ipm, /install, 'http://packages.idldev.com/mgunit.zip'
```

Bi-directional bridge lets you easily run IDL routines or ENVI analytics from your language of choice

Can also use ENVI Py to call ENVI Tasks

IDL-Python Bridge

```
3  from idlpy import IDL
4  import numpy as np
5  import os
6
7  #start ENVI
8  e = IDL.envi(HEADLESS = 1)
9
10 # get task definition from IDL
11 task = IDL.ENVITask("BuildMosaicRaster")
12 task.INPUT_RASTERS = rasters
13 task.RESAMPLING = 'Nearest Neighbor'
14 task.FEATHERING_METHOD = 'edge'
15 task.OUTPUT_RASTER_URI = e.GetTemporaryFilename()
16 task.execute()
17
```

ENVI Py Directly

```
1  from envipyengine import Engine
2  from envipyarc import GPToolbox
3  import arcpy
4
5  # make toolbox
6  engine = Engine('ENVI')
7  task_list = [engine.task('SpectralIndex')]
8  envi_toolbox = GPToolbox(task_list)
9  toolbox_file = envi_toolbox.create_toolbox('c:\\my_envi_tools')
10 arcpy.ImportToolbox(toolbox_file)
11
12 # run the toolbox
13 input_raster = 'C:/Program Files/Harris/ENVI54/data/qb_boulder_msi'
14 index = 'Normalized Difference Vegetation Index'
15 result = arcpy.SpectralIndex_envi(input_raster,index)
16 print(result)
```

Use IDL to create a [Scikit-learn](#) classifier:

```
1 ; Read data
2 read_seeds_example_data, data, labels, $
3   N_ATTRIBUTES=nAttributes, N_EXAMPLES=nExamples, $
4   N_LABELS=nLabels, UNIQUE_LABELS=uniqueLabels
5
6 ; Import scikit-learn and our classifier
7 >>>import sklearn
8 >>>from sklearn.ensemble import RandomForestClassifier
9
10 ; Create a random forest classifier
11 clf = python.RandomForestClassifier(n_estimators = 25, max_depth = 5, $
12   min_samples_split = 2, random_state = 42)
13
14 ; fit to the data - transpose because python is row major, not column major
15 clf = clf.fit(transpose(data), labels)
16
17 ; Classify the first example
18 print, clf.predict(data[:,0]), /IMPLIED_PRINT
19
20 ; specify a file to save the model to
21 tempFile = 'C:\users\username\mymodel.p'
22
23 ; import the pickle module
24 pickle = python.import('pickle')
25
26 ; Save the model for later with the latest, most efficient protocol
27 !NULL = pickle.dump(clf, python.open(tempfile, 'wb'), protocol=-1)
```

Use ENVI from Python to read data for [Keras](#):

```
1 import * from idlpy
2 import numpy as np
3 import keras
4
5 # start ENVI **must be headless**
6 e = IDL.envi(HEADLESS = 1)
7
8 # load a previously saved model
9 modelFile = 'C:\\users\\username\\mymodel.h5'
10
11 # load the model
12 clf = keras.models.load_model(modelFile)
13
14 # read some data from a raster
15 raster = e.openRaster('C:\\users\\username\\myraster.dat')
16 dat = np.transpose(raster.getData())
17
18 # classify the data
19 # TODO: extract chips first then predict in batches
20 classified = clf.predict(data)
21
22 # create output raster and save result
23 outRaster = IDL.ENVIraster(np.transpose(classified),
24   URI = 'C:\\users\\username\\myraster.dat')
25 outRaster.save()
```

GitHub (<https://github.com/>):

- A development platform for hosting git repositories
- Free for open-source projects
- Extensive userbase
- More than just source control



Git (<https://git-scm.com/>):

- A tool for source control of files, most often code
- Track changes, merge branches of code, and makes examining previous work easy
- CLI or UI



We are on GitHub!


ENVI and IDL GitHub organizations:

- <https://github.com/envi-idl>
- <https://github.com/interactive-data-language>

For this webinar, “IDL Packages” are synonymous with GitHub repositories

GitHub repositories are meant for source code, but you can store other types of files there

Releases are snapshots of a repository and releases can have additional files attached (i.e. compiled source code)



When anyone can contribute to an open source, IDL package, how do you verify code integrity and usability?

One-stop-shop to ensure code integrity by providing a simple platform for:

- Writing and running unit tests
- Generating documentation
- Compiling source code

Inspired by [npm](#), [yarn](#), and the [Angular CLI](#)

Open sourced (coming soon) for community-driven development

Built around GitHub's rest API

Two types of packages: global and local

Local packages are for development and advanced users

Global packages are for deployment

Object based API and CLI for executing commands

```
1 ; open our global package
2 c = idlpc()
3
4 ; open a local package
5 c = idlpc('C:\some\folder\on\disk\my-package')
6
7 ; shortcut to open a local package if on search path
8 c = idlpc('my-package')
```

```
C:\>ipc --global remove uavtoolkit
Licensed for use by: Harris Geospatial Tradeshow
License: MNT-5507041:****_****_****-D10E
License expires 4-Jan-2019.
Using global installation location
WARNING: Entry point not specified in idl.package.json file
Processing dependencies
Removed package "github-uavtoolkit"
C:\>ipc --global add uavtoolkit
Licensed for use by: Harris Geospatial Tradeshow
License: MNT-5507041:****_****_****-D10E
License expires 4-Jan-2019.
Using global installation location
Retrieving package information for "envi-idl/UAVToolkit"
Resolving dependencies...
Installed package "github-uavtoolkit" with release tag "^v2.3.3"
```


Unit tests are critical for writing dependable code

Sol: Test runner, wrapped by the IDL Package Creator

Luna: Test writer for individual files

Code coverage and profiling

Inspired by Jasmine and Karma

```
compile_opt idl2

; main level program (Luna can only be instantiated in a main level program)
l = luna(/PROFILE)

;create a test suite
s = l.suite('Sample test suite which has a few tests with' )

;create a test for our suite
it = s.test('a test with expectations that pass')

;make sure our routine runs
(it.expects('example')).toRunProcedure

; summarize our tests
l.generateTestSummary
end
```

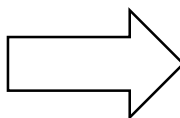
Existing solution is [idldoc](#)

Based on markdown, uses [pandoc](#)

Used for generating the courses for ENVI + IDL

Live example: <https://envi-idl.github.io/UAVToolkit/>

```
;  
;+  
; :Examples:  
;   See ![FILE:./README.md] for examples of how to use this routine.  
;  
; :Description:  
;   Simple routine that can be used to perform input validation  
;   for any routine to ensure that parameters are present or a  
;   certain type. You can specify each possible type that the  
;   data value can represent and optionally require that the value have  
;   all of the types. Here are the generic types that can be used:  
;  
;   - required : If set, the value must be present and defined.  
;  
;   - array    : If set, value supplied must be an array.  
;  
;   - number   : If set, value supplied must be a number.  
;  
;   - file     : If set, value must be a file on disk.  
;  
;   - directory: If set, value must be a folder on disk.  
;  
;   This routine uses IDL's `isa` function to make the comparison so,  
;   in addition to the types above, you can specify anything else that  
;   can pass as an argument. Some examples are: byte, int, long, float,  
;   hash, orderedhash, enviroaster. They can be any IDL-specific data  
;   type and it can also be the type of object such as idlgrwindow or  
;   any named, custom object type.  
;  
; :Params:
```



AwesomeLabelRegions

This task uses IDL's `label_region()` on images in a tiled fashion. Because this uses `label_region()` it focuses on processing binary images with pixels values that are zero or nonzero. The out-of-the-box LabelRegions algorithm works with images that are non-binary (i.e. classification images) and, understanding that, this task is for a specific use case: binary datasets.

For binary images, this routine is about 2x faster than the LabelRegions task. For a 120 MB binary mask with 10980 columns and rows here are performance metrics:

AwesomeLabelRegions : 8.6 seconds
LabelRegions : 16 seconds

COPY

Here is an example of how you can run this routine:

```
; Start the application  
e = envi()  
  
; load our awesome algorithms  
awesomeENVIALgorithms, /INIT  
  
; Open an input file  
File = filepath('qb_boulder_msi', SUBDIR = ['data'], $  
  ROOT_DIR = e.ROOT_DIR)
```

COPY

Compiling source code is not hard to do, but repetitive
Can be a hassle to do over and over again
Will automatically run unit tests before building
Resolves all dependencies into a single entry point

```
IDL> c.build, /NO_TEST
WARNING: Tests skipped per user request
Cleaning up existing folder...
Building package in "C:\Users\Traininglead\Documents\github\Tasks\SE-AwesomeENVIAlgorithms\dist" with types:
idl

Building type "idl"...
  Searching for files to copy and build...
  Found files to process...
  Initializing child process...
  Copying and building files, may take a minute or two...
    Resolving dependencies
    Dependencies resolved in:
      C:\Users\Traininglead\Documents\github\Tasks\SE-AwesomeENVIAlgorithms\dist\awesomeenvialgorithms.sav
  Copying and building additional files, may take a minute or two...
  Zipping contents
  Cleaning up

Successfully built package!
```

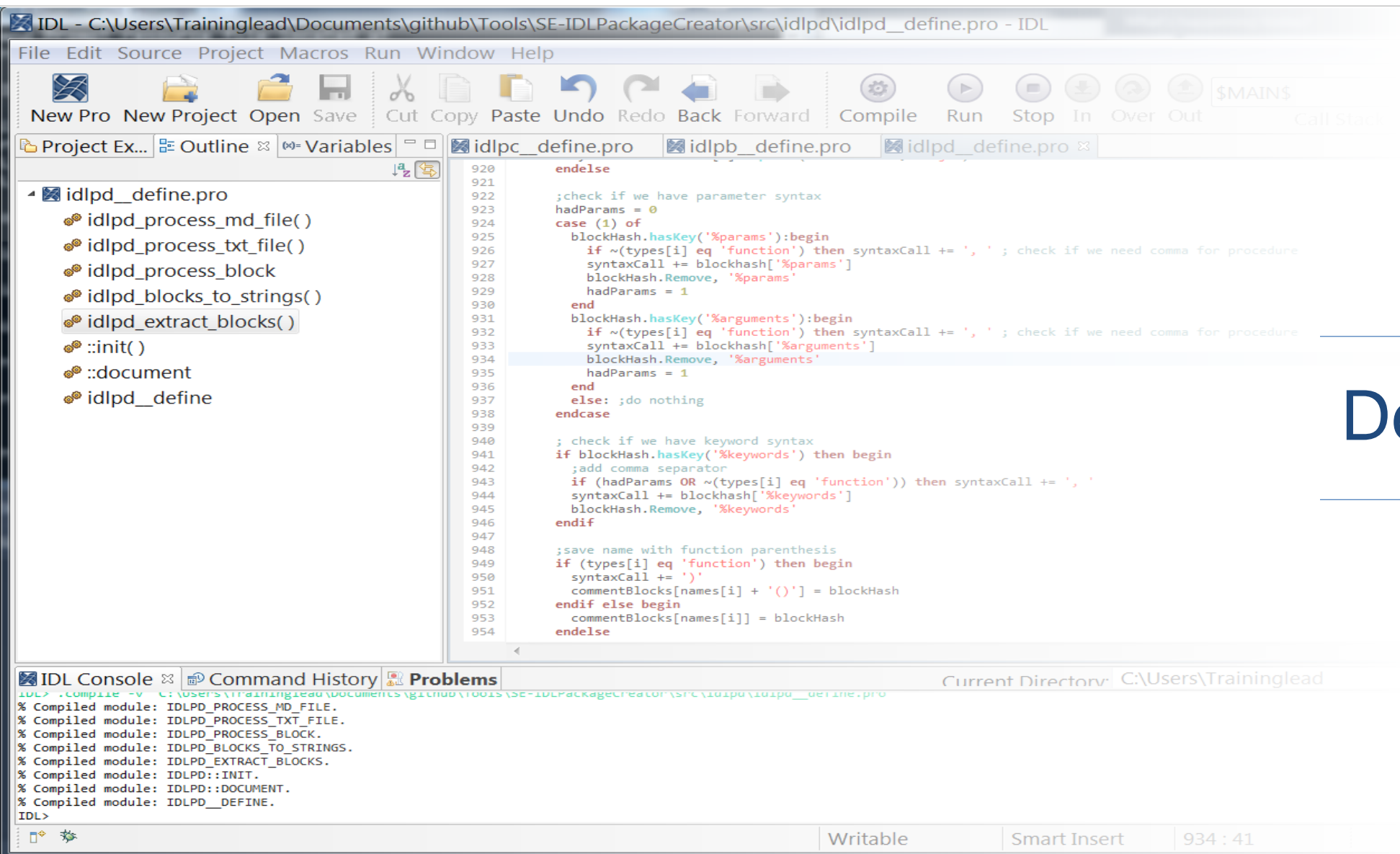
Upcoming:

- IDLPackageCreator
- AwesomeENVITools
- AwesomeENVIAlgorithms
- MaskingToolkit

Existing Packages:

- UAVToolkit
- FXExtras





The screenshot displays the IDL IDE interface. The main editor window shows the file `idlpc_define.pro` with the following code:

```

920     endwhile
921
922     ;check if we have parameter syntax
923     hadParams = 0
924     case (1) of
925         blockHash.hasKey('%params'):begin
926             if ~(types[i] eq 'function') then syntaxCall += ', ' ; check if we need comma for procedure
927             syntaxCall += blockhash['%params']
928             blockHash.Remove, '%params'
929             hadParams = 1
930         end
931         blockHash.hasKey('%arguments'):begin
932             if ~(types[i] eq 'function') then syntaxCall += ', ' ; check if we need comma for procedure
933             syntaxCall += blockhash['%arguments']
934             blockHash.Remove, '%arguments'
935             hadParams = 1
936         end
937     else: ;do nothing
938     endcase
939
940     ; check if we have keyword syntax
941     if blockHash.hasKey('%keywords') then begin
942         ;add comma separator
943         if (hadParams OR ~(types[i] eq 'function')) then syntaxCall += ', '
944         syntaxCall += blockhash['%keywords']
945         blockHash.Remove, '%keywords'
946     endif
947
948     ;save name with function parenthesis
949     if (types[i] eq 'function') then begin
950         syntaxCall += '()'
951         commentBlocks[names[i] + '()'] = blockHash
952     endif else begin
953         commentBlocks[names[i]] = blockHash
954     endwhile

```

The left sidebar shows the project structure for `idlpc_define.pro`, including submodules like `idlpc_process_md_file()`, `idlpc_process_txt_file()`, `idlpc_process_block`, `idlpc_blocks_to_strings()`, `idlpc_extract_blocks()`, `::init()`, `::document`, and `idlpc_define`.

The bottom panel shows the IDL console output, which lists the compiled modules:

```

IDL> .Compile -v C:\Users\Traininglead\Documents\github\Tools\SE-IDLPackageCreator\src\idlpc\idlpc_define.pro
% Compiled module: IDLPD_PROCESS_MD_FILE.
% Compiled module: IDLPD_PROCESS_TXT_FILE.
% Compiled module: IDLPD_PROCESS_BLOCK.
% Compiled module: IDLPD_BLOCKS_TO_STRINGS.
% Compiled module: IDLPD_EXTRACT_BLOCKS.
% Compiled module: IDLPD::INIT.
% Compiled module: IDLPD::DOCUMENT.
% Compiled module: IDLPD_DEFINE.
IDL>

```

The status bar at the bottom indicates the current directory is `C:\Users\Traininglead` and shows the file is writable, smart insert is enabled, and the cursor is at line 934, column 41.

Demo!

Contest!



Based around open sourced IDL Packages

Two categories:

1. ENVI
2. IDL

Winners get free attendance to the ENVI Analytics Symposium and opportunity to speak at the VIP Customer Summit

Additional details coming soon on criteria and submissions



Follow up email will be sent with whitepaper on open source technologies when the packages are placed on GitHub

<https://www.harrisgeospatial.com/Company/Contact-Us>

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